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SOFTWARE FOR THE PARALLEL SOLUTION OF SYSTEMS OF ORDINARY DIFFERENTIAL EQUATIONS

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Software for the Parallel Solution of Systems of Ordinary Differential Equations

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Abstract

This report contains software for the solution of systems of ordinary differential equations on an INTEL iPSC/2 hypercube. A diskette is available upon request from the second author.

1. Introduction

In this report we supply software for the numerical solution of systems of ordinary differential equations (ODEs) on an INTEL iPSC/2 hypercube. The first program can only be used to solve *linear* initial or boundary value systems of ODEs and based on an algorithm developed by Katti and Neta (1989) and improved by Lustman *et al* (1990). The second program is based on polynomial extrapolation and Gragg's scheme and is useful for nonlinear ODEs as well. This algorithm is described in Lustman, Neta and Gragg (1991).

2. Linear Systems

In this section we give the software for the solution of *linear* systems of ODEs:

$$
\begin{aligned}
&y'(x) = Ay(x) + g(x), \ a < x < b \\
&y(a) = y_a
\end{aligned}
\tag{1}
$$

The algorithm used was developed by Katti and Neta (1989) and improved by Lustman *et al* (1990). The host and node program are given. The subroutines sa, sf and putex give the matrix A, the right hand side of (1) and the exact solution (for debugging purposes) respectively. An example of input and output corresponding to these subroutines are attached.

```
c
c
c                          HOST
c solving initial value problems by multiple shooting
c on INTEL iPSC/2 hypercube having 8 (maxnp) processors
c
c                 see  Lustman, Neta & Katti
c
c change everywhere, in both node and host programs,
c                 ndim=3
c to whatever value is appropriate.
c
      program mshivph
      integer intype,inlen,outype,outlen
      integer ymtype,ymlength
      integer n ,np,ndim,nin,nout, m , mnp
      integer allnodes,hostpid,nodepid
      parameter (nmax=100)
      parameter (ndim=3,nout=1)
     parameter(maxnp=8)
      parameter (nin=nmax*maxnp+ndim+10)
      parameter (intype=10,outype=20,inlen=4*nin
     # ,ymtype=30,ymlength=ndim*(ndim+1)*4
     # ,outlen=4*nout,allnodes= -1
     # ,hostpid=8,nodepid=14)
      common/cin/n,ndimc,ninc,noutc
     #,m,mp,h,left,right,g,x
      real g (ndim) , x (0:nmax*maxnp) , vin (1)
      real vout (nout) , left , right
     equivalence
     # (n,vin(1)),(ndimc,vin(2)),(ninc,vin(3))
     #,(noutc,vin(4)),(m,vin(5)),(mp,vin(6))
     #,(h,vin(7)),(left,vin(8)),(right,vin(9))
     #,(g(1),vin(10))
     #,(x(0),vin(10+ndim))
      ndimc=ndim
      ninc=nin
      noutc=nout
      call getcube('shoot',' ',' ',1)
      call setpid(hostpid)
       print*,' got the maximal cube,',numnodes(),' nodes'
      call load('node',allnodes,nodepid)
      print*,' after load'
      print*,' enter ',ndim,' initial values g'
      read*,(g(i),i=1,ndim)
      print*,' enter endpoints of interval'
      read*,left,right
      print*,'solve for ',left,' <x< ',right
     ,,' initially=',(g(i),i=1,ndim)
      print*,' enter number of points in interval, for each proc
      read*,m
      print*,m,' points for each processor'
      np=numnodes()
      mnp=m*np
      h=(right-left)/mnp
```

```
      do 400 i=0,mnp
400   x(i)=left+(i)*h
      call csend(intype,vin,inlen,allnodes,nodepid)
411   continue
      call waitall(allnodes,nodepid)
      call relcube('shoot')
      stop
      end
```

```
c
c                          NODE
c solving initial value problems by multiple shooting
c on INTEL iPSC/2 hypercube having 8 (maxnp) processors
c
c                see  Lustman, Neta & Katti
c
c Change everywhere, in both node and host programs,
c                ndim=3
c to whatever value is appropriate.
c
c The subroutines       sa (computing the matrix A) and
c                        sf (the right hand side)
c                       putex ( the exact solution, needed for deb
c
c must be supplied for each application. (Examples are given in th
c
         program MSHIVPN
         integer intype,inlen,outype,outlen
         integer ymtype,ymlen,ymdim,cubdimax
         integer n ,np,ndim,nin,nout, m , mnp ,ready
         integer allnodes,hostpid,nodepid
        integer tend,tbeg
         parameter (nmax=100)
         parameter (ndim=3,nout=1)
        parameter(maxnp=8)
         parameter (nin=nmax*maxnp+ndim+10)
         parameter (intype=10,outype=20,inlen=4*nin
     # ,cubdimax=3,ymtype=300,ymdim=ndim*(ndim+1) )
        parameter (ymlen=4+ymdim*4
     # ,outlen=4*nout,allnodes= -1
     # ,hostpid=8,nodepid=14)
        common/cin/n,ndimc,ninc,noutc
     #,m,mp,h,left,right,g,x
         real g (ndim) , x (0:nmax*maxnp) , vin (nin)
        real vym(0:ymdim,0:cubdimax)
        real vym0(0:ymdim)
         real vout (nout) , left , right
        equivalence
     # (n,vin(1)),(ndimc,vin(2)),(ninc,vin(3))
     #,(noutc,vin(4)),(m,vin(5)),(mp,vin(6))
     #,(h,vin(7)),(left,vin(8)),(right,vin(9))
     #,(g(1),vin(10))
     #,(x(0),vin(10+ndim))
        dimension phiex(ndim),phi(ndim),ytilde(ndim)
        dimension er(ndim)
        dimension ucphi(ndim,ndim),binv(ndim,ndim)
        real a(ndim,ndim),b(ndim,ndim)
        dimension ynit(ndim),partic(ndim)
        call crecv(intype,vin,inlen)
        me=mynode()
        numno=numnodes()
        jl=me*m
        jh=jl+m
c
```

```
c initialization
c
        call init(ndim,ucphi,ytilde)
        xme=jh*h+left
cdebug  call putex(xme,phiex,g)
        do 100 j=jl,jh-1
        xx=x(j)+0.5*h
c
c get A
c
        call sa(ndim,xx,a)
c
c get B=I - h/2 A
c
        call sb(h,ndim,a,b)
c
c evaluate B inverse
c
        call sbinv(b,binv,ndim)
c
c evaluate D = Binv *(I + h/2 A)
c
        call sd(binv,h,ndim,a,b)
c
c multiply ucphi*B
c
        call smult(ucphi,b,ndim)
c
c get right hand side
c
        call sf(ndim,xx,f)
c
c get phi
c
        call sphi(b,ytilde,h,binv,f,ndim,phi)
c
c copy phi to ytilde
c
        if(j.lt.jh-1) then
        call scopy(phi,ytilde,ndim)
        endif
 100    continue
c
c the following starts with initial conditions
c
        if(me.eq.0) call sma(ucphi,g,phi,ndim)
c
c here the process of recursive doubling
c
        jq=me+1
        iq=1
1132    continue
c
c send to  some node after me
c
```

```
        if(jq+iq.le.numno) then
c
c make a list of data to send in the buffer vym0
c
        call enlist(me,phi,ucphi,vym0,ndim)
        call csend(ymtype+me,vym0,ymlen,iq+me,nodepid)
        endif
c
c  y1j = bj =phi j
c  m1j = phi j
c
 1133   continue
        if(me.ge.iq) then
c
c       me  requires data from  me-iq
c
c
        call crecv (ymtype+me-iq,vym0,ymlen)
        do 58 i=1,ndim+ndim*ndim
58      vym(i,1)=vym0(i)
c
c y1 =y1 + M * y0
c
        call defy(ndim,phi,ucphi,vym(1,1))
c
c M = M * M0
c
        call defm(ndim,ucphi,vym(ndim+1,1))
        endif
        iq=2*iq
        if(iq.lt.numno) goto 1132
c
c end of processing
c
c       iunit=10+me
cdebug   do 1001 i=1,ndim
cdebug 1001     er(i)=abs(phi(i)-phiex(i))
        print1000,xme,phi
 1000   format('x=',f6.2,' phi=',3f6.2)
cdebug  print1001,er
cdebug 1001     format(8x,' err=',3f6.2)
        stop
        end
c
c makes a list of values to send in the buffer v
c
        subroutine enlist(me,phi,ucphi,v,n)
        dimension v(0:1),phi(n),ucphi(n,n)
        v(0)=me
        l=1
        do 1 i=1,n
        v(l)=phi(i)
        l=l+1
 1      continue
        do 2 j=1,n
```

```
      do 2 i=1,n
      v(l)=ucphi(i,j)
      l=l+1
 2    continue
      return
      end
c
c computes B= I - h/2 A
c
      subroutine sb(h,ndim,a,b)
c evaluate b=i-h/2*a
      real a(ndim,ndim),b(ndim,ndim)
      do 10 i=1,ndim
      do 10 j=1,ndim
      r=0
      if(i.eq.j) r=1
      b(i,j)=r-0.5*h*a(i,j)
 10   continue
      return
      end
c
c computes D= Binv * ( I + h/2 A )
c
      subroutine sd(binv,h,ndim,a,b)
      real a(ndim,ndim),b(ndim,ndim),binv(ndim,ndim)
      do 10 i=1,ndim
      do 10 j=1,ndim
      b(i,j)=0
      do 10 k=1,ndim
      r=0
      if(k.eq.j) r=1
      b(i,j)=b(i,j)+binv(i,k)*(r+0.5*h*a(k,j))
 10   continue
      return
      end
c
c evaluate b*ucphi into ucphi
c
      subroutine smult(ucphi,b,idim)
       parameter (ndim=3)
      real ucphi(idim,idim),b(idim,idim)
      real temp(ndim)
      do 100 j=1,idim
      do 10 i=1,idim
      temp(i)=0
      do 10 k=1,idim
      temp(i)=temp(i)+b(i,k)*ucphi(k,j)
 10   continue
      do 20 k=1,idim
 20   ucphi(k,j)=temp(k)
 100  continue
      return
      end
c
c evaluate d*ytilde + h*binv*f
```

```
c
        subroutine sphi(b,ytilde,h,binv,f,ndim,phi)
        real b(ndim,ndim),ytilde(ndim),binv(ndim,ndim)
        real f(ndim),phi(ndim)
        do 10 i=1,ndim
        phi(i)=0
        do 10j=1,ndim
 10     phi(i)=phi(i)+b(i,j)*ytilde(j)+h*binv(i,j)*f(j)
        return
        end
c
c moves phi to ytilde
c
        subroutine scopy(phi,ytilde,ndim)
        real ytilde(ndim),phi(ndim)
        do 10 i=1,ndim
 10     ytilde(i)=phi(i)
        return
        end
c
c evaluate ucphi*g +phi and put into phi
c
        subroutine sma(ucphi,g,phi,ndim)
        real phi(ndim),ucphi(ndim,ndim),g(ndim)
        do 10 i=1,ndim
        do 10 j=1,ndim
 10     phi(i)=phi(i)+ucphi(i,j)*g(j)
        return
        end
c
c initialize ucphi and ytilde
c
        subroutine init(ndim,ucphi,ytilde)
        real ytilde(ndim),ucphi(ndim,ndim)
        do 10 i=1,ndim
        ytilde(i)=0
        do 20 j=1,ndim
        ucphi(i,j)=0
 20     continue
        ucphi(i,i)=1
 10     continue
        return
        end
c
c inverts b into binv . b is destroyed
c                    ==================
c
        subroutine sbinv(b,binv,ndim)
        real b(ndim,ndim),binv(ndim,ndim)
        do 20 i=1,ndim
        do 10 j=1,ndim
 10     binv(i,j)=0
 20     binv(i,i)=1
        do 2 j=1,ndim
        z=1/b(j,j)
```

```
      do 30 k=1,ndim
      b(j,k)=z*b(j,k)
      binv(j,k)=z*binv(j,k)
 30   continue
      do 1 i=1,ndim
      if(i.eq.j) goto 1
      z=b(i,j)
      do 3 k=1,ndim
      b(i,k)=b(i,k)-z*b(j,k)
      binv(i,k)=binv(i,k)-z*binv(j,k)
 3    continue
 1    continue
 2    continue
      return
      end
c
c evaluates Y1=Y1+M*Y0
c
      subroutine defy(ndim,y1,em,y0)
      dimension y1(ndim),em(ndim,ndim),y0(ndim)
      do 1 i=1,ndim
      do 1 j=1,ndim
      y1(i)=y1(i)+em(i,j)*y0(j)
 1    continue
      return
      end
c
c evaluates M=M*M0
c
      subroutine defm(ijmax,em,em0)
       parameter (ndim=3)
      dimension row(ndim)
      dimension em(ijmax,ijmax),em0(ijmax,ijmax)
      do 1 i=1,ijmax
      do 3 j=1,ijmax
      row(j)=em(i,j)
 3    continue
      do 1 j=1,ijmax
      s=0
      do 2 k=1,ijmax
      s=s+row(k)*em0(k,j)
 2    continue
      em(i,j)=s
 1    continue
      return
      end
cdebugc
cdebugc given x, and initial values g, computes v=exact(x)
cdebugc
cdebug  subroutine putex(x,v,g)
cdebug  parameter (ndim=3)
cdebug  parameter(e=2.718281828,ei=1./e)
cdebug  dimension v(ndim),g(ndim)
cdebug  dimension v(3)
cdebug  real l0g
```

```
cdebug  ex=exp(x)
cdebug  l0g=alog(x)
cdebug  a=(g(1)-1)*ei
cdebug  b=(g(2)-e)*ei
cdebug  c=(g(3)-ei)*ei
cdebug  v(1)=ex*(a+l0g*(b+c/2*l0g))+1
cdebug  v(2)=ex*(b+c*l0g)+ex
cdebug  v(3)=ex*c+1/ex
cdebug  return
cdebug  end
c
c evaluate right hand side f(x)
c
        subroutine sf(idim,x,f)
        parameter (ndim=3)
        real x, f(idim)
        ex=exp(x)
        f(1)=-1-ex/x
        f(2)=-1/x/ex
        f(3)=-2/ex
        return
        end
c
c evaluate the matrix A(x)
c
        subroutine sa(ndim,x,a)
        real a(ndim,ndim),x
        do 10 i=1,ndim
        do 10 j=1,ndim
        a(i,j)=0
 10     continue
        a(1,1)=1
        a(2,2)=1
        a(3,3)=1
        a(1,2)=1/x
        a(2,3)=1/x
        return
        end
```

```
# This file is used to compile and link the host.f, node.f
#
# The command "make all" causes compilation and linking.


all :   host node


host:   host.o
        f77 -o host host.o -host


node:   node.f
        f77 -o node node.f -node



***********************************************
            example of an input file
            for the subroutine sa, sf, putex
            currently in node.f
***********************************************
0,0,0   initial values
1,2       endpoints
5       subintervals for each processor



***********************************************
            example of output file for the above
***********************************************
  got the maximal cube,           8 nodes
  after load
  enter            3 initial values g
  enter endpoints of interval
 solve for    1.000000     <x<    2.000000
initially=  0.0000000E+00  0.0000000E+00  0.0000000E+00
  enter number of points in interval, for each processor
          5 points for each processor
x=  1.13 phi= -0.50 -0.05 -0.09
x=  1.25 phi= -1.07 -0.11 -0.19
x=  1.38 phi= -1.74 -0.17 -0.28
x=  1.50 phi= -2.52 -0.25 -0.38
x=  1.63 phi= -3.42 -0.33 -0.49
x=  1.75 phi= -4.46 -0.44 -0.61
x=  1.88 phi= -5.67 -0.55 -0.73
x=  2.00 phi= -7.08 -0.69 -0.86

        (may appear in a different order, each line written by a
         different processor, when it is ready)
```

3. Nonlinear Systems

The algorithm used is based on Gragg's Method (1964,1965) and polynomial extrapolation as described by Lustman, Neta and Gragg (1991). One can solve

$$\begin{aligned} y'(x) &= f(x, y(x)) \\ y(a) &= y_a \end{aligned} \tag{2}$$

where y and f are vector valued functions and y_a is a vector of initial values.

The host and node programs are supplied along with exa.f file containing subroutines for the evaluation of the exact solution (putex) and the right hand side (rhs) of (2). The make file to compile and link these programs is given at the end followed by an example of input and output files for the given putex and rhs.

```
c
c               HOST
c        program for the solution of nonlinear systems
c       based on Gragg's method and polynomial extrapolation
c       on INTEL iPSC/2 having 8 (maxproc) processors
c
c      see Lustman, Neta and Gragg
c
c   leny0   =  length of vector of initial values
c   nptmax  =  maximum number of points in common to all processors
c
        implicit double precision (a-h,o-z)
        parameter(leny0=20,nptmax=100)
        parameter(maxproc=8,iv=5)
        parameter(initype=1000,inilen=4*(iv+leny0)
     ,,nodes=-1,idhost=2,nodepid=3)
        dimension y0(leny0),sendata(iv+leny0)
        call getcube('extrap',' ',' ',1)
        call setpid(idhost)
        nproc=numnodes()
         print*,' got the maximal cube,',nproc,' nodes'
        call load('node',nodes,nodepid)
c
c  xmin, xmax = the interval of integration
c
        print*,'Enter xmin,xmax'
        read*,xmin,xmax
        print*,'How many result points (excluding xmin)?'
        read*,npt
        print*,'Enter dimension of solution vector'
        read*,leny
        if(leny.gt.leny0) then
        print*,'dimension=',leny,'>',leny0
        stop
        endif
        print*,'Enter ',leny,' initial values'
        read*,(y0(i),i=1,leny)
cdebugc if debugging, replace the two lines above by
cdebug  call putex(xmin,leny,y0)
           print*,'How many processors will be used?'
        read*,nn
        if(nn.gt.nproc.or.nn.lt.1) then
        print*,nn,' is unreasonable. '
        nn=nproc
        endif
        nproc=nn
        print*,' will use ',nproc,' processors'
        sendata(1)=xmin
        sendata(2)=xmax
        sendata(3)=leny
        sendata(4)=npt
        sendata(5)=nproc
        do 1 j=1,leny
 1      sendata(iv+j)=y0(j)
        call csend(initype,sendata,inilen,nodes,nodepid)
```

```
      call waitall(nodes,nodepid)
      call relcube('extrap')
      stop
      end
```

```
c
c                NODE
c        program for the solution of nonlinear systems of ODEs
c       based on Gragg's method and polynomial extrapolation
c       on INTEL iPSC/2 having 8 (maxproc) processors
c
c      see Lustman, Neta and Gragg
c
        implicit double precision (a-h,o-z)
        parameter(leny0=20,nptmax=100)
        parameter(maxproc=8,iv=5)
        parameter(iii=5,jdata=iii+leny0+nptmax*leny0)
        parameter(initype=1000,inilen=4*(iv+leny0)
     ,,nodes=-1,idhost=2,nodepid=3)
        dimension y0(leny0),dataini(iv+leny0)
        dimension ysave(leny0,0:nptmax)
     ,,y(leny0),yexa(leny0),hlfway(leny0)
        dimension data(jdata)
        dimension hvec(0:maxproc)
        me=mynode()
        iam=me
        call crecv(initype,dataini,inilen)
        xmin=   dataini(1)
        xmax=   dataini(2)
        leny=   dataini(3)
        npt=    dataini(4)
        nproc=  dataini(5)
        lastproc=(nproc-1)
        if(iam.gt.lastproc) stop
        jdta=iii+leny+npt*leny
c
c ABSOLUTELY ESSENTIAL: 8 bytes per double precision item
c
         lendta=8*jdta

c
c message length in bytes
c

        ne=nproc-me
c
c save results every ne steps
c
        do 1 j=1,leny
 1      y0(j) = dataini(iv+j)
        ipow=1
c
c all the h's must be known to all the processors
c
        do 10 i=0,nproc-1
        hvec(i)=(xmax-xmin)/(npt*(nproc-i))
 10     continue
        h=hvec(me)
c
c fixes the size for integration.
```

```
c
        jndex=0
        do 2 j=1,leny
        ysave(j,jndex)=y0(j)
 2      y(j)=y0(j)
        do 3 index=1,npt*(ne)
        x=xmin+h*(index-1)
        call odestep(h,x,y,index,hlfway,leny)
c
c advances the solution
c in this form, it is a two step method, i.e.
c       h,x,y(x)  and y(x-h/2) is what you need to obtain y(x+h)
c
        if(mod(index,ne).eq.0) then
c
c save this result, it belongs to a common point
c
        jndex=jndex+1
        do 4 j=1,leny
        ysave(j,jndex)=y(j)
 4      continue
        endif
 3      continue

        if(me.ne.lastproc) then
c
c send my saved data to lastproc (who probably is done by now)
c
        l=iii
        if(jndex.ne.npt) then
        print*,' i am ',me,' jndex=',jndex
     ,,' .ne. npt=',npt
        stop
        endif
        do 6 j=0,npt
        do 6 i=1,leny
        l=l+1
        data(l)=ysave(i,j)
 6      continue
        call csend(me,data,lendta,lastproc,nodepid)
        endif
c
c i am waiting for data to do extrapolations on
c
        level=nproc-me
c
c the new data will be sent to me-1 with superscript level
c
c

        msgtyp=(me)
        if(me.eq.lastproc) msgtyp=(me-1)
 134    continue
        call crecv(msgtyp,data,lendta)
        if(msgtyp.eq.me) then
```

```
c
c just save the message in ysave
c
        l=iii
        do 69 j=0,npt
        do 69 i=1,leny
        l=l+1
        ysave(i,j)=data(l)
 69     continue
        else
c
c extrapolate incoming data and ysave
c
        it=     data(1)
        itsne=  data(2)
        itspow= data(4)
        hish=   data(5)
c
c because the error goes in powers of h**2
c
        w=1/(   (hvec(msgtyp)/hvec(msgtyp+level))**2   -1)
        l=iii
        do 7 j=0,npt
        do 7 i=1,leny
        l=l+1
        z=data(l)
        data(l)= ysave(i,j)+w*(ysave(i,j)-data(l))
        ysave(i,j)=z
c
c This prepares extrapolated data to send and saves
c the data received to extrapolate with other message data
c

 7      continue

        call csend(msgtyp,data,lendta,me-1,nodepid)
        endif
        msgtyp=msgtyp-1
        if(msgtyp.ge.0) goto 134
        if(me.ne.0) goto 1512
c
c everything done, report results
c
        hout=(xmax-xmin)/npt
        orm=0
        er=0
        do 9 j=0,npt
        x=xmin+j*hout
cdebug  call putex(x,leny,yexa)
        print900,j,x
 900    format(i5,f10.3)
        do 8 i=1,leny
        print800,ysave(i,j)
cdebug     ,,yexa(i),abs(ysave(i,j)-yexa(i))
cdebug  orm=orm+yexa(i)**2
```

```
cdebug  er=er+(ysave(i,j)-yexa(i))**2
 800    format(2f10.3,1pe10.2)
 8      continue
 9      continue
cdebug  print900, -999,-999.
cdebug  orm=sqrt(orm)
cdebug  er=sqrt(er)
cdebug  reler=er/orm
cdebug  print800, orm,er,reler
 1512   continue
        end
c
c    subroutine for ode stepping using Gragg's method
c
        subroutine odestep(h,x,y0,index,hlfway,l)
c
c y0,hlfway are input and output. the step is from x=x to x=x+h
c
        implicit double precision (a-h,o-z)
        parameter(leny0=20,nptmax=100)
        dimension y0(l),hlfway(l),r(leny0)
        if(index.eq.1) then
c
c this is the first step
c
        call rhs(x,y0,l,r)
        do 61 i=1,l
 61     hlfway(i)=y0(i)+h/2*r(i)
        else
c
c the general step : hlfway is at x-h/2, y0 at x
c       they advance to x+h/2, x+h correspondingly
c
        call rhs(x,y0,l,r)
        do 661 i=1,l
 661    hlfway(i)=hlfway(i)+h*r(i)
        endif
        call rhs(x+h/2,hlfway,l,r)
        do 662 i=1,l
 662    y0(i)=y0(i)+h*r(i)

c
c Gragg formula. the errors go in powers of h**2
c
        return
        end
```

```
c
c              EXA.F
c
c   putex evaluates the exact solution
c   for this examples y(i) exact = x **i
c
        subroutine putex (x,l,y)
        implicit double precision (a-h,o-z)
        dimension y(l)
        y(1)=x
        do 1 j=2,l
        y(j)=x*y(j-1)
 1      continue
        return
        end
c
c   evaluates the right hand side for the above system
c
        subroutine rhs (x,y,l,r)
        implicit double precision (a-h,o-z)
        dimension y(l),r(l)
        x2=x*x
        div=x2*x
        do 1 i=1,l-1
        r(i)=i*y(i)*y(i+1)/div
        div=div*x
 1      continue
        r(l)=l*y(l)*y(1)/x2
        return
        end
```

```
#
#                  this is the makefile
# this file is used to compile and link the host.f, node.f
#
# the command "make all" causes compilation and linking.


all :   exa.o host node

exa.o:  exa.f

host:   host.f exa.o
        f77 -o host exa.o host.f -host


node:   node.f  exa.o
        f77 -o node exa.o node.f -node


*********************************************
             example of input file for
             the subroutines in exa.f
*********************************************

1,2
2
4
1,1,1,1
5


*********************************************
             example of output file for
             the above input
*********************************************
  got the maximal cube,           8 nodes
 Enter xmin,xmax
 How many result points (excluding xmin)?
 Enter dimension of solution vector
 Enter            4 initial values
 How many processors will be used?
  will use            5 processors


    0     1.000
     1.000
     1.000
     1.000
    1     1.500
     1.500
     2.250
     3.375
     5.062
```

```
 2     2.000
  2.000
  4.000
  8.000
 15.999
```

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